Social Choice Theory and Machine Learning Lecture 3

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August 7, 2024

Plan for today

- \checkmark A brief introduction to social choice theory
- $\sqrt{ }$ A survey of voting methods
- \checkmark Characterizing voting methods
- $\sqrt{\ }$ Splitting cycles and breaking ties
- \blacktriangleright Stable Voting
- ▶ Preferential Voting Tools
- ▶ Learning voting rules

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W. Holliday and E. Pacuit. Stable Voting. Constitutional Political Economy, 2023.

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Find the first match such that a wins according to Simple SV after b is removed from all ballots; this a is the winner for the original set of ballots.

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In fact, SV has a remarkable ability to avoid ties even in elections with small numbers of voters that can produce tied margins.

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Re 2, the frequency with which Stable Voting violates monotonicity is minuscule compared to the frequency for Instant Runoff (in use in the Bay Area and NYC).

StableVoting.org

Stable Voting is a free and easy way to make a group decision by voting.

Create a poll and send the generated link to your voters.

Voters rank the candidates.

View the winner and explanation of results.

StableVoting.org

Stable Voting has a remarkably low tie frequency, making it very useful in elections with even small numbers of voters.

Over 200 real elections have already been run on [StableVoting.org.](https://stablevoting.org)

People have voted on all kinds of issues:

- ▶ electing leaders and officials, such as presidents of organizations, boards of directors, union representatives;
- ▶ choosing names for children, pets, groups, etc.;
- ▶ planning social events and gatherings, like trips, parties, and outings;
- soliciting entertainment preferences, about books, TV shows, and movies;
- \triangleright deciding miscellaneous organizational matters, such as meeting times, rules, and procedures

Please try the website and let us know what you think!

Using axioms to evaluate voting methods

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Suppose that a voting method F violates an axiom while the voting method G satisfies the axiom.

- \blacktriangleright How likely is it that F violates the axiom (with respect to some probability model generating elections)?
- \blacktriangleright How likely is it that F violates the axiom conditional on F and G selecting different winners (with respect to some probability model generating elections)?

Preferential Voting Tools

More than 70 voting methods (including voting methods for different ballot types) are implemented in our Preferential Voting Tools Python package (<https://pref-voting.readthedocs.io/>)

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 $= r + m$

Brief Introduction to the Preferential Voting Tools

Other ways to evaluate voting methods

- \triangleright Utility: Given the utilities of the voters, which voting method comes as close as possible to maximizing *social utility*?
- \triangleright Epistemic: Assuming that the ballots are noisy signals from the voters about some "correct" alternative (or ranking), which voting method is more likely to select the correct alternative (or ranking)?
- ▶ Computational: What is the complexity of finding the winner? What information from the voters is needed to compute the winner?
- ▶ Strategic: To what extent does the voting method incentivize *strategic* voting? Or strategic agenda setting?

Course Plan

- introduction to mathematical analysis of voting methods, voting paradoxes;
- probabilistic voting methods (skipped for now);
- \checkmark quantitative analysis of voting methods (e.g., Condorcet efficiency);
- learning voting rules (PAC-learning, MLPs, other approaches);
- using modern deep learning techniques to generate synthetic election data;
- strategic voting, learning to successfully manipulate voting rules based on limited information about how the other voters will vote using neural networks (multi-layer perceptrons);
- ▶ RLHF (reinforcement learning with human feedback) and social choice;
- using large-language models to improve group decision-making; and
- \blacktriangleright liquid democracy (time permitting).

PAC-Learning of Voting Methods

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 \triangleright An entity, which is referred to as the designer, has in mind a voting rule (which may reflect the ethics of a society). It is assumed that the designer is able, for each constellation of voters' preferences with which it is presented, to designate a winning alternative (perhaps with considerable computational effort).

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- \blacktriangleright In particular, one can think of the designer's representation of the voting rule as a black box that matches preference profiles to winning alternatives. This setting is relevant, for example, when a designer has in mind different properties it wants its rule to satisfy; in this case, given a preference profile, the designer can specify a winning alternative that is compatible with these properties.

- ▶ The goal is to find a concise and easily understandable representation of the voting rule that the designer has in mind.
- \triangleright Automated design of voting rules: given a specification of properties, or, indeed, of societal ethics, find an elegant voting rule that implements the specification.

- ▶ The goal is to find a concise and easily understandable representation of the voting rule that the designer has in mind.
- \triangleright Automated design of voting rules: given a specification of properties, or, indeed, of societal ethics, find an elegant voting rule that implements the specification.
- \triangleright Assume further that the "target" voting rule the designer has in mind, i.e., the one given as a black box, is known to belong to some family $\mathcal R$ of voting rules. We would like to produce a voting rule from R that is as "close" as possible to the target rule.

Introduction to PAC-Learning

- ▶ PAC (Probably Approximately Correct) learning is a theoretical framework for understanding the feasibility of learning.
- \blacktriangleright It aims to define the conditions under which a learner can learn a function that generalizes well from a limited set of training examples.
- \blacktriangleright The learner tries to find a hypothesis h from a hypothesis class H that approximates a target function f^* .
- \triangleright The goal is to ensure that with high probability, the hypothesis has an error less than a specified threshold *ϵ*.

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▶ Error of a function $f \in \mathcal{F}$:

$$
err(f) = \Pr_{z \sim D}[f(z) \neq f^*(z)]
$$

Accuracy and Confidence

Accuracy parameter $\epsilon > 0$: Desired accuracy of the learning process. **►** Confidence parameter $\delta > 0$: Probability that error exceeds ϵ :

 $Pr[err(h) > \epsilon] < \delta$

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- \triangleright L is an *efficient learning algorithm* if it always runs in time polynomial in $1/\epsilon$ 1/ δ , and the size of the representations of the target function, of elements in Z , and of elements in Y .

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- A function class F is (efficiently) PAC-learnable if there is an (efficient) learning algorithm for \mathcal{F} .

Theorem

The class of scoring rules for *n* voters and *m* candidates efficiently PAC-learnable.

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"It is rather straightforward to construct an efficient algorithm that outputs consistent scoring rules. Given a training set, we must choose the parameters of our scoring rule in a way that, for any example, the score of the designated winner is at least as large as the scores of other alternatives. Moreover, if ties between the winner and a loser would be broken in favor of the loser, then the winner's score must be strictly higher than the loser's."

for
$$
k \leftarrow 1...s
$$
 do
\n $X_k \leftarrow \emptyset$
\nfor all $x_j \neq x_{j_k}$ do
\n $\vec{\pi}^{\Delta} \leftarrow \vec{\pi}_{j_k}^k - \vec{\pi}_{j}^k$
\n $l_0 \leftarrow \min\{l: \pi_l^{\Delta} \neq 0\}$
\nif $\pi_{l_0}^{\Delta} < 0$ then
\n $X_k \leftarrow X_k \cup \{x_j\}$
\nend if
\nend for
\nend for

 \triangleright x_{i_k} is the winner in example k

 \triangleright Ties are broken in favor of x_i

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return a feasible solution $\vec{\alpha}$ to the following linear program:

$$
\forall k, \ \forall x_j \in X_k, \sum_l \pi^k_{j_k,l} \alpha_l \geqslant \sum_l \pi^k_{j_l,l} \alpha_l + 1
$$
\n
$$
\forall k, \ \forall x_j \notin X_k, \ \sum_l \pi^k_{j_k,l} \alpha_l \geqslant \sum_l \pi^k_{j,l} \alpha_l
$$
\n
$$
\forall l = 1, \dots, m - 1 \quad \alpha_l \geqslant \alpha_{l+1}
$$
\n
$$
\forall l, \ \alpha_l \geqslant 0
$$

\nfor
$$
k \leftarrow 1 \ldots s
$$
 do\n $X_k \leftarrow \emptyset$ \n for all $x_j \neq 0$.\n for all $x_j \neq 0$.\n for all $x_j \neq 0$.\n $\vec{\pi}^{\Delta} \leftarrow \vec{\pi}$ \n for all $x_j \neq 0$.\n $\vec{\pi}^{\Delta} \leftarrow \vec{\pi}$ \n for all $x_j \neq 0$.\n X_{jk} is the winner in election k .\n $\vec{\pi}^{\Delta} \leftarrow a \in X_k$ means that ties between a and x_{j_k} .\n $\vec{\pi}^{\Delta} \leftarrow a$

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for $k \leftarrow 1...s$ do $X_{\nu} \leftarrow \emptyset$ for all $x_i \neq x_{i_k}$ do \triangleright x_i is the winner in example k $\vec{\pi}^{\Delta} \leftarrow \vec{\pi}_{i}^{k} - \vec{\pi}_{i}^{k}$ $l_0 \leftarrow \min\{l: \pi_l^{\Delta} \neq 0\}$ if $\pi_{l_0}^{\Delta}$ < 0 then \triangleright Ties are broken in favor of x_i $X_k \leftarrow X_k \cup \{x_i\}$ end if end for end for **return** a feasible solution $\vec{\alpha}$ to the following linear program: $\forall k, \ \forall x_j \in X_k, \sum_l \pi_{i_l,l}^k \alpha_l \geqslant \sum_l \pi_{i,l}^k \alpha_l + 1$ $\forall k, \ \forall x_j \notin X_k, \sum_l \pi_{i_l,l}^k \alpha_l \geq \sum_l \pi_{i,l}^k \alpha_l$ $\forall l = 1, \ldots, m-1 \quad \alpha_l \geqslant \alpha_{l+1}$ $\forall l, \alpha_l \geqslant 0$

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Given examples that are consistent with some general voting rule, is it possible to learn a scoring rule (or a small voting tree) that is "close" to the target rule?

Fix n voters and m candidates. A voting method \overline{F} is a c-approximation of a voting rule G provided that F and G agree on a c-fraction of the profiles:

$$
|\{\mathbf{P} \mid F(\mathbf{P}) = G(\mathbf{P})\}| \ge c \times (m!)^n.
$$

Theorem (Procaccia et al. 2009)

Let \mathcal{R}_m^n be a family of voting rules of size exponential in n and m, and let $\epsilon, \delta > 0$. For large enough values of *n* and *m*, at least a $(1 - \delta)$ -fraction of the voting rules F satisfy the following property: no voting rule in ${\cal R}^n_m$ is a $(1/2 + \epsilon)$ -approximation of F.

Corollary (Procaccia et al. 2009)

For large enough values of n and m , almost all voting rules cannot be approximated by a scoring rule on n and m to a factor better than $1/2$.